MASTER HANDBOOK OF

ACOUSTICS



F. ALTON EVEREST & KEN C. POHLMANN

Master Handbook of Acoustics

About the Authors

F. Alton Everest was a leading expert and authority in the field of acoustics. He was an emeritus member of the Acoustical Society of America, a life member of the Institute of Electrical and Electronics Engineers, and a life fellow of the Society of Motion Picture and Television Engineers. He was cofounder and director of the Science Film Production division of the Moody Institute of Science, and was also section chief of the Subsea Sound Research section of the University of California.

Ken C. Pohlmann is well known as an audio educator, consultant, and author. He was director of the Music Engineering Technology program, founder of its Master of Science degree program, and is professor emeritus, at the University of Miami in Coral Gables, Florida. He is a fellow of the Audio Engineering Society, a consultant for numerous audio companies and car manufacturers, and an expert in patent-infringement litigation. He is author of numerous articles and books including *Principles of Digital Audio* (McGraw-Hill), and coauthor of the *Handbook of Sound Studio Construction* (McGraw-Hill).

Contributions are included from Peter D'Antonio, Geoff Goacher, and Doug Plumb.

Master Handbook of Acoustics

F. Alton Everest Ken C. Pohlmann

Seventh Edition



New York Chicago San Francisco Athens London Madrid Mexico City Milan New Delhi Singapore Sydney Toronto Copyright © 2022, 2015, 2009, 2001 by McGraw Hill. All rights reserved. Except as permitted under the United States Copyright Act of 1976, no part of this publication may be reproduced or distributed in any form or by any means, or stored in a database or retrieval system, without the prior written permission of the publisher.

ISBN: 978-1-26-047360-5 MHID: 1-26-047360-0

The material in this eBook also appears in the print version of this title: ISBN: 978-1-26-047359-9,

MHID: 1-26-047359-7.

eBook conversion by codeMantra Version 1.0

All trademarks are trademarks of their respective owners. Rather than put a trademark symbol after every occurrence of a trademarked name, we use names in an editorial fashion only, and to the benefit of the trademark owner, with no intention of infringement of the trademark. Where such designations appear in this book, they have been printed with initial caps.

McGraw-Hill Education eBooks are available at special quantity discounts to use as premiums and sales promotions or for use in corporate training programs. To contact a representative, please visit the Contact Us page at www.mhprofessional.com.

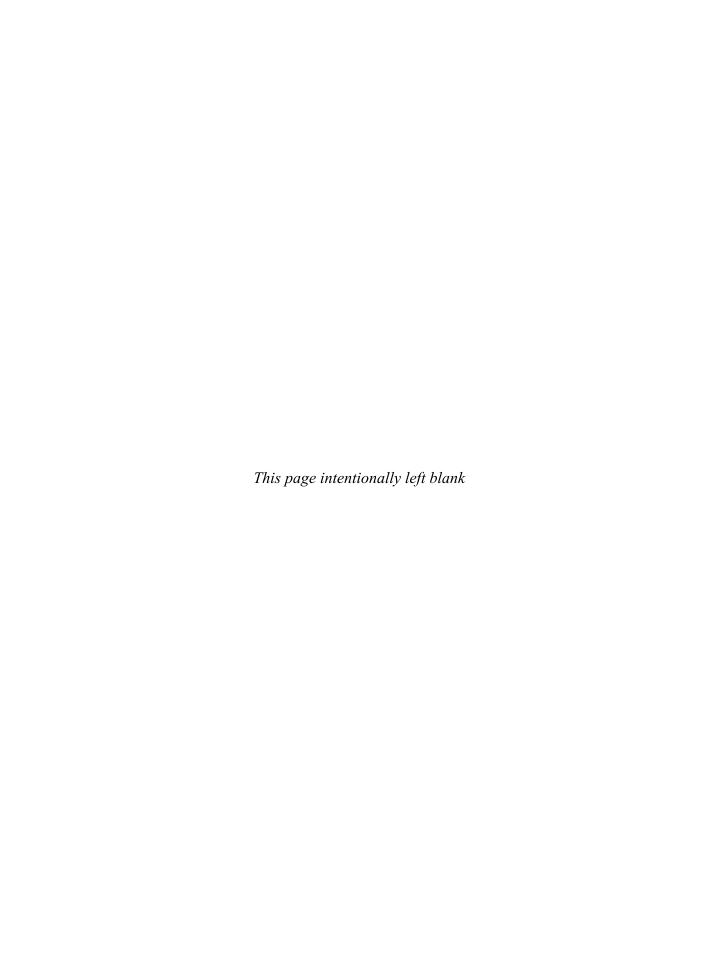
Information contained in this work has been obtained by McGraw Hill from sources believed to be reliable. However, neither McGraw Hill nor its authors guarantee the accuracy or completeness of any information published herein, and neither McGraw Hill nor its authors shall be responsible for any errors, omissions, or damages arising out of use of this information. This work is published with the understanding that McGraw Hill and its authors are supplying information but are not attempting to render engineering or other professional services. If such services are required, the assistance of an appropriate professional should be sought.

TERMS OF USE

This is a copyrighted work and McGraw-Hill Education and its licensors reserve all rights in and to the work. Use of this work is subject to these terms. Except as permitted under the Copyright Act of 1976 and the right to store and retrieve one copy of the work, you may not decompile, disassemble, reverse engineer, reproduce, modify, create derivative works based upon, transmit, distribute, disseminate, sell, publish or sublicense the work or any part of it without McGraw-Hill Education's prior consent. You may use the work for your own noncommercial and personal use; any other use of the work is strictly prohibited. Your right to use the work may be terminated if you fail to comply with these terms.

THE WORK IS PROVIDED "AS IS." McGRAW-HILL EDUCATION AND ITS LICENSORS MAKE NO GUARANTEES OR WARRANTIES AS TO THE ACCURACY, ADEQUACY OR COMPLETENESS OF OR RESULTS TO BE OBTAINED FROM USING THE WORK, INCLUDING ANY INFORMATION THAT CAN BE ACCESSED THROUGH THE WORK VIA HYPERLINK OR OTHERWISE, AND EXPRESSLY DISCLAIM ANY WARRANTY, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. McGraw-Hill Education and its licensors do not warrant or guarantee that the functions contained in the work will meet your requirements or that its operation will be uninterrupted or error free. Neither McGraw-Hill Education nor its licensors shall be liable to you or anyone else for any inaccuracy, error or omission, regardless of cause, in the work or for any damages resulting therefrom. McGraw-Hill Education has no responsibility for the content of any information accessed through the work. Under no circumstances shall McGraw-Hill Education and/or its licensors be liable for any indirect, incidental, special, punitive, consequential or similar damages that result from the use of or inability to use the work, even if any of them has been advised of the possibility of such damages. This limitation of liability shall apply to any claim or cause whatsoever whether such claim or cause arises in contract, tort or otherwise.





Contents

	Introduction	xix
1	Fundamentals of Sound Simple Harmonic Motion and the Sine Wave Sound in Media Particle Motion Propagation of Sound Speed of Sound Wavelength and Frequency Complex Waveforms Harmonics Phase Partials Octaves Spectrum Key Points	1 2 3 4 5 7 7 8 8 10 13 13 15 18
2	Sound Levels and the Decibel Ratios versus Differences	19 19 20 21 21 23 24 25 26 29 30 32
3	Sound in the Free Field The Free Field Sound Divergence Sound Intensity in the Free Field Sound Pressure in the Free Field Free-Field Sound Divergence Sound Fields in Enclosed Spaces Hemispherical Field and Propagation Key Points	35 35 35 36 37 37 39 41

viii Contents

4	The Perception of Sound 4	.3
	Sensitivity of the Ear 4	:3
	Ear Anatomy 4	4
	The Outer Ear—Pinna 4	:5
	A Demonstration of Directional Cues 4	:5
	The Outer Ear—Auditory Canal 4	:5
	The Middle Ear 4	:6
	The Inner Ear 4	8:
	Stereocilia 4	9
	Loudness versus Frequency	0
	Loudness Control 5 5.	2
	Area of Audibility 5.	2
	Loudness versus Sound-Pressure Level 5.	3
	Loudness and Bandwidth 5	5
	Loudness of Impulses 5	7
	Audibility of Loudness Changes	8
	Pitch versus Frequency 5	
	An Experiment in Pitch	
	The Missing Fundamental	
	Timbre versus Spectrum 6	
	Localization of Sound Sources	0
	Binaural Localization 6	3
	Law of the First Wavefront	
	The Franssen Effect 6	4
	The Precedence (Haas) Effect	4
	Perception of Reflected Sound	5
	The Cocktail-Party Effect 6	7
	Aural Nonlinearity 6	8
	Subjective versus Objective Evaluation 6	8
	Occupational and Recreational Hearing Loss 6	9
	Key Points 7	1
_		
5	Signals, Speech, Music, and Noise	
	Sound Spectrograph	-
	Speech	
	Vocal Tract Molding of Speech	
	Formation of Voiced Sounds	
		7
	Frequency Response of Speech	
	Directionality of Speech	
	Music 7	
	String Instruments	
	Wind Instruments	
	Nonharmonic Overtones	
	Dynamic Range of Speech and Music	
	Power in Speech and Music 8	З

	Frequency Range of Speech and Music	84
	Auditory Area of Speech and Music	84
	Noise	86
	Noise Measurements	87
	Random Noise	88
	White and Pink Noise	89
		9:
	Signal Distortion	
	Harmonic Distortion	92
	Resonance	95
	Audio Filters	96
	Key Points	99
6	Reflection	101
U		101
	Specular Reflections	
	Flutter Echoes	103
	Doubling of Pressure at Reflection	104
	Reflections from Convex Surfaces	104
	Reflections from Concave Surfaces	105
	Reflections from Parabolic Surfaces	105
	Whispering Galleries	105
	Standing Waves	107
	Corner Reflectors	107
	Mean Free Path	108
	Perception of Sound Reflections	108
	The Effect of Single Reflections	108
	Perception of Spaciousness, Images, and Echoes	111
	Effect of Angle of Incidence, Signal Type, and Spectrum	
	on Audibility of Reflection	111
	Key Points	112
	Key I onitis	112
7	Diffraction	115
	Diffraction and Wavefront Propagation	115
	Diffraction and Wavelength	116
	Diffraction by Obstacles	116
	Diffraction by Apertures	119
	Diffraction by a Slit	120
	Differentian by a Zone Plate	120
	Diffraction by a Zone Plate	
	Diffraction around the Human Head	120
	Diffraction by Loudspeaker Cabinet Edges	120
	Diffraction by Various Objects	124
	Key Points	124
8	Refraction	125
J	The Nature of Refraction	125
	Refraction in Solids	126
	Refraction in the Atmosphere	
	1	127
	Refraction in Enclosed Spaces	130

χ Contents

	Refraction in the Ocean Key Points	130 131
9	Diffusion The Perfectly Diffuse Sound Field Evaluating Diffusion in a Room Steady-State Measurements Decay Beats Exponential Decay Spatial Uniformity of Reverberation Time Geometrical Irregularities Absorbent in Patches Concave Surfaces Convex Surfaces: The Polycylindrical Diffuser Plane Surfaces Key Points	133 134 134 135 135 136 139 140 140 142 142
10	Comb-Filter Effects Comb Filters Superposition of Sound Tonal Signals and Comb Filters Comb Filtering of Music and Speech Signals Comb Filtering of Direct and Reflected Sound Comb Filters and Critical Bands Comb Filters in Multichannel Playback Controlling Comb Filtering Reflections and Spaciousness Comb Filters in Microphone Placement Comb-Filter Effects in Practice: Six Examples Estimating Comb-Filter Response Key Points	143 143 144 146 147 151 152 153 153 154 157 159
11	Reverberation Growth of Sound in a Room Decay of Sound in a Room Idealized Growth and Decay of Sound Calculating Reverberation Time Sabine Equation Eyring-Norris Equation Air Absorption Measuring Reverberation Time Impulse Sources Steady-State Sources Measuring Equipment Measurement Procedure	161 163 163 164 165 167 168 169 170 171
	Reverberation and Normal Modes Analysis of Decay Traces	171 173

	Mode Decay Variations	173
	Frequency Effect	175
	Reverberation Characteristic	175
	Reverberation Time Variation with Position	176
	Decay Rate and the Reverberant Field	176
	Acoustically Coupled Spaces	178
	Electroacoustically Coupled Spaces	178
	Eliminating Decay Fluctuations	179
	Influence of Reverberation on Speech	179
	Influence of Reverberation on Music	180
	Optimum Reverberation Time	181
	Bass Rise of Reverberation Time	184
	Initial Time-Delay Gap	185
	Listening Room Reverberation Time	185
	Artificial Reverberation	186
	Examples of Reverberation Time Calculations	188
	Key Points	190
	•	
12	Absorption	193
	Dissipation of Sound Energy	193
	Absorption Coefficients	194
	Reverberation Chamber Method	196
	Impedance Tube Method	196
	Tone-Burst Method	198
	Mounting of Absorbents	200
	Mid/High-Frequency Absorption by Porosity	201
	Glass-Fiber Low-Density Materials	201
	Glass-Fiber High-Density Boards	203
	Glass-Fiber Acoustical Tile	204
	Effect of Thickness of Absorbent	205
	Effect of Airspace behind Absorbent	205
	Effect of Density of Absorbent	205
	Open-Cell Foams	206
	Drapes as Sound Absorbers	208
	Carpet as Sound Absorber	210
	Effect of Carpet Type on Absorbance	212
	Effect of Carpet Underlay on Absorbance	212
	Carpet Absorption Coefficients	
	Sound Absorption by People	213
	Sound Absorption in Air	215
	Panel (Diaphragmatic) Absorbers	215
	Polycylindrical Absorbers	220
	Polycylindrical Absorber Construction	222
	Bass Traps: Low-Frequency Absorption by Resonance	223
	Helmholtz (Volume) Resonators	224
	Perforated Panel Absorbers	227

xii Contents

	Slat Absorbers	231
	Placement of Materials	231
	Reverberation Time of Helmholtz Resonators	231
	Reducing Room Modes with Absorbers	234
	Increasing Reverberation Time	236
	Absorption Module Design	236
	Key Points	238
	Key 1 onto	200
13	Modal Resonances	241
	Early Experiments and Examples	241
	Resonance in a Pipe	242
	Resonance in a Pipe Indoor Reflections	244
	Two-Wall Resonance	246
	Frequency Regions	247
	Room-Mode Equation	249
		250
	Mode Calculations—An Example	
	Experimental Verification	253
	Mode Decay	254
	Mode Bandwidth	255
	Mode Pressure Plots	260
	Mode Density	263
	Mode Spacing and Timbral Defects	264
	Audibility of Timbral Defects	265
	Optimal Room Proportions	266
	Bonello Criterion	269
	Splaying Room Surfaces	269
	Nonrectangular Rooms	270
	Controlling Problem Modes	273
	Simplified Axial-Mode Analysis	273
	Key Points	275
	Tay 1 onto	2,0
14	Schroeder Diffusers	277
	Experimentation	277
	Reflection Phase-Grating Diffusers	278
	Quadratic Residue Diffusers	279
	Primitive Root Diffusers	280
	Performance of Diffraction-Grating Diffusers	281
	Reflection Phase-Grating Diffuser Applications	283
	Flutter Echo	287
	Application of Fractals	289
	Diffusion in Three Dimensions	292
	Diffusing Concrete Blocks	293
	Measuring Diffusion Efficiency	293
	Comparison of Gratings with Conventional Approaches	295
	Key Points	297
15	Adjustable Acoustics	299
13		299
	Draperies	ムフン

Contents		iii
	/41	

	Portable Absorptive Panels	300
	Hinged Panels	303
	Louvered Panels	303
	Absorptive/Diffusive Adjustable Panels	304
	Variable Resonant Devices	305
	Rotating Elements	306
	Modular Low-Frequency Absorptive Devices	308
	Key Points	311
16	Sound Isolation and Site Selection	313
10		314
	Propagation through Barriers	
	Approaches to Noise Control	314
	Airborne Noise	315
	Transmission Loss	316
	Effect of Mass and Frequency	317
	Coincidence Effect	318
	Separation of Mass	319
	Porous Materials	319
	Sound Transmission Class	320
	Structureborne Noise	322
	Noise Transmitted by Diaphragmatic Action	323
	Noise and Room Resonances	323
	Site Selection	323
	The Noise Survey	325
	Assessment of Environmental Noise	328
	Measurement and Testing Standards	329
	Recommended Practices	330
	Noise Measurements and Construction	332
	Floor Plan Considerations	334
	Designing within a Frame Structure	335
	Designing within a Concrete Structure	335
	Key Points	335
17	Sound Isolation: Walls, Floors, and Ceilings	337
	Walls as Effective Noise Barriers	337
	The Role of Porous Absorbers	338
	The Mass Law and Wall Design	339
	Separation of Mass in Wall Design	342
	Wall Design Summary	345
	Improving an Existing Wall	350
	Flanking Sound	351
	Gypsum Board Walls as Sound Barriers	351
	Masonry Walls as Sound Barriers	352
	,	
	Weak Links	355
	Summary of Wall STC Ratings	356
	Floating Floors	358
	Floating Walls and Ceilings	360
	Resilient Hangers	361

xiv Contents

	Floor/Ceiling Construction	362
	Case Study of Footfall Noise	363
	Floor/Ceiling Structures and Their IIC Performance	365
	Floor/Ceilings in Frame Buildings	365
	Floor Attenuation with Concrete Layers	366
	Plywood Web versus Solid Wood Joists	368
	Key Points	370
18	Sound Isolation: Windows and Doors	371
	Single-Pane Windows	372
	Double-Pane Windows	373
	Acoustical Holes in Glass: Mass-Air-Mass Resonance	374
	Acoustical Holes in Glass: Coincidence Resonance	376
	Acoustical Holes in Glass: Standing Waves in the Cavity	377
	Glass Mass and Spacing	378
	Dissimilar Panes	380
	Laminated Glass	380
	Plastic Panes	380
	Slanting the Glass	381
	Third Pane	381
	Cavity Absorbent	381
	Thermal Glass	381
	Example of an Optimized Double-Pane Window	381
	Construction of an Observation Window	382
	Proprietary Observation Windows	385
	Sound-Isolating Doors	386
	Sound Locks	390
	Composite Partitions	390
	Key Points	392
	•	-
19	Noise Control in Ventilating Systems	393
	Selection of Noise Criteria	393
	Fan Noise	396
	Machinery Noise and Vibration	398
	Air Velocity	401
	Natural Attenuation	402
	Duct Lining	403
	Plenum Silencers	405
	Proprietary Attenuators	406
	Reactive Silencers	407
	Tuned Silencers	408
	Duct Location	408
	ASHRAE	409
	Active Noise Control	410
	Key Points	411
20	Acoustics of Listening Rooms and Home Theaters	413
	Playback Criteria	413

	Planning the Playback Room	415
	Acoustical Treatment of Playback Rooms	416
	Peculiarities of Small-Room Acoustics	416
	Room Size and Proportion	417
	Reverberation Time	417
	Low-Frequency Considerations	417
	Modal Anomalies	421
	Control of Modal Resonances	421
	Bass Traps for Playback Rooms	421
	Mid/High-Frequency Considerations	423
	Identification and Treatment of Reflection Points	425
	Lateral Reflections and Control of Spaciousness	426
	Loudspeaker Placement	427
	Listening Room Plan	428
	Home-Theater Plan	431
	Controlling Early Reflections	433
	Other Treatment Details	434
	Key Points	437
21	Acoustics of Home Studios	439
41	Home Acoustics: Modes	439
	Home Acoustics: Reverberation	440
	Home Acoustics: Noise Control	440
	Home Studio Budget	441
	Home Studio Treatment	442
	Home Studio Plan	444
	Recording in the Home Studio	446
	Garage Studio	448
	Key Points	449
22	Acoustics of Small Recording Studios	451
	Ambient Noise Requirements	451
	Acoustical Characteristics of Small Studios	452
	Direct and Indirect Sound	452
	Role of Room Treatment	452
	Room Modes and Room Volume	454
	Mode Analysis for Different Room Sizes	454
	Reverberation Time	456
	Reverberation in Small Rooms	456
	Optimal Reverberation Time	457
	Diffusion	457
	Noise	458
	Small Studio Design Example	458
	Absorption Design Goal	458
	Proposed Room Treatment	459
	Key Points	463

xvi Contents

23	Acoustics of Large Recording Studios	465
	Design Criteria of a Large Studio	466
	Floor Plan	466
	Wall Sections	466
	Section D-D	467
	Section E-E	469
	Sections F-F and G-G	470
	Studio Treatment	470
	Drum Booth	472
	Vocal Booth	473
	Sound-Lock Corridor	475
	Reverberation Time	475
	Key Points	477
24	Acoustics of Control Rooms	479
	Initial Time-Delay Gap	479
	Live End-Dead End	481
	Specular Reflections versus Diffusion	482
	Low-Frequency Resonances in Control Rooms	484
	Initial Time-Delay Gaps in Practice	485
	Loudspeaker Placement, Reflection Paths, and Near-Field	405
	Monitoring	485
	The Reflection-Free-Zone Control Room	487
	Control-Room Frequency Range	489
	Outer Shell and Inner Shell of the Control Room	490 490
	Design Criteria of a Control Room	490
	Design Example 1: Control Room with Rectangular Walls	491
	Design Example 2: Double-Shell Control Room with Splayed Walls	493
	Design Example 3: Single-Shell Control Room with Splayed Walls Key Points	494
		490
25	Acoustics of Isolation Booths	499
	Applications	499
	Design Criteria	500
	Isolation Requirements	501
	The Small-Room Problem	501
	Design Example 1: Traditional Isolation Booth	502
	Axial Modes	503
	Reverberation Time	503
	Design Example 2: Isolation Booth with Cylindrical Traps	505
	Acoustical Measurements	510
	Reverberation Time	510
	Design Example 3: Isolation Booth with Diffusers	512
	Reverberation Time	514
	Evaluation and Comparison	515
	Live End–Dead End Isolation Booth	519
	Key Points	519

C	0	n	t	е	n	t	S	xvii	
---	---	---	---	---	---	---	---	------	--

26	Acoustics of Audiovisual Postproduction Rooms	521
	Design Criteria	521
	Design Example 1: Small Postproduction Room	522
	Appraisal of Room Resonances	522
	Proposed Treatment	522
	Design Example 2: Large Postproduction Room	526
	Appraisal of Room Resonances	526
	Monitor Loudspeakers and Early Sound	526
	Late Sound	530
	Proposed Treatment	531
	Workbench	534
	Mixing Engineer's Workstation	534
	Video Display and Lighting	535
	Key Points	536
27	Acoustics of Teleconference Rooms	537
	Design Criteria	537
	Shape and Size of the Room	538
	Floor Plan	539
	Ceiling Plan	539
	Elevation Views	540
	Reverberation Time	541
	Key Points	543
28	Acoustics of Large Halls	545
	Design Criteria	546
	Reverberation and Echo Control	546
	Air Absorption	548
	Hall Design for Speech	549
	Volume	549
	Hall Geometry	549
	Absorption Treatment	551
	Ceiling, Walls, and Floor	551
	Speech Intelligibility	552
	Speech Frequencies and Duration	552
	Subject-Based Measures	552
	Analytical Measures	552
	Concert Hall Acoustical Design	554
	Reverberation	554
	Clarity	555
	Brilliance	555
	Gain	555
	Seating Capacity	556
	0 - 1 - 1	
	Volume	
		556
	Diffusion	556 557
		556

xviii Contents

	Initial Time-Delay Gap	557
	Bass Ratio and Warmth	558
	Concert Hall Architectural Design	558
	Balcony	558
	Ceiling and Walls	559
	Raked Floor	560
	Virtual Image Source Analysis	560
	Hall Design Procedure	562
	Case Studies	562
	Postscript	564
	Key Points	565
A	Overview of TDS and MLS Analysis	569
В	Room Auralization	575
C	Selected Absorption Coefficients	587
	Bibliography	589
	Glossary	605
	Index	619

Introduction

ou hold in your hands, either physically or electronically, the seventh edition of the *Master Handbook of Acoustics*. Mr. F. Alton Everest was the original author of this book. In 1981 he devised the formula for an acoustics book that balanced theory and practice. Many engineering books sprinkle examples and problems throughout the text, to inform the reader of practical applications. He improved on that model by presenting basic theory combined with a significant quantity of pragmatic information, then attaching entire chapters, comprising a substantial portion of the book, that are purely devoted to practical examples. These chapters are particularly essential for anyone building a room with similar characteristics.

Mr. Everest understood that this was the perfect way to teach introductory acoustics while simultaneously providing practical guidance to anyone undertaking a construction project. He thus created a valuable tool that we know and trust, a book that has become a classic. The acoustical engineering community grieved when Mr. Everest passed away in 2005 at the age of 95.

I was honored when McGraw-Hill asked me to prepare a fifth, a sixth, and now this seventh edition of the Master Handbook of Acoustics. I had used the handbook since it was first published, and was well familiar with its value as a teaching text and reference handbook. Readers who are familiar with another of my books, Principles of Digital Audio, may be surprised to learn that my passion for digital technology is equaled by my enthusiasm for acoustics. I taught courses in architectural acoustics (in addition to classes in digital audio) for 30 years at the University of Miami, where I directed the Music Engineering Technology program. Throughout that time, I also consulted on many acoustics projects, ranging from recording studio to listening room design, from church acoustics to community noise intrusion. As with many practitioners in the field, it was important for me to understand the fundamentals of acoustical properties, to be able to articulate those principles to clients, and also to stay current with the practical applications and solutions to today's acoustical problems. This essential equilibrium was the guiding principle of Mr. Everest's original vision for this book, and I have continued to seek that same balance. Further, through Mr. Everest's four editions, and my three editions, this book has improved steadily to reach a high level of refinement.

Occasionally, and particularly among newbies to the field of acoustics, the question arises, "Why is it important to study acoustics?" One reason, among many, is that you will be joining in, and hopefully contributing to, a noble scientific undertaking. Since antiquity, some of the world's greatest scientists and engineers have studied acoustics and its elegant complexities. Greek philosophers including Pythagoras, Aristotle, and

xx Introduction

Euclid began the exploration of the nature of musical harmonics and how we hear sound. The great Roman engineer and architect Vitruvius carefully analyzed echo and reverberation in his building projects. Over the years, heavyweights such as Ptolemy, Galileo, Mersenne, Kircher, Hooke, Newton, Laplace, Euler, D'Alembert, Bernoulli, Lagrange, Poisson, Faraday, Helmholtz, Ohm, Doppler, and Sabine all made contributions. In all, countless men and women have worked to evolve the science of acoustics to a high degree of sophistication.

But, pressing the question, in today's binary world, is acoustics still important? Consider this: We rely on our eyes and ears. Our eyes close when we sleep; we cannot see in the dark; someone can sneak up on us unseen from behind. But from birth to death, awake or asleep, in light and in dark, our ears are always sensitive to our world around us. Whether we are hearing sounds that give us pleasure, or sounds that alert us to danger, whether they are sounds of nature, or sounds of technology, the properties of acoustics and the way that architectural spaces affect those sounds are woven into every moment of our lives. Is acoustics important? I think it is. And I'm pretty sure Mr. Everest would agree.

Ken C. Pohlmann

CHAPTER 1

Fundamentals of Sound

Sound can be considered as wave motion in air or other elastic media. In this case, sound acts as a stimulus. Sound can also be considered as an excitation of the hearing mechanism that results in its perception. In this case, sound is a sensation. This duality of sound is familiar to those interested in audio and music. The type of problem at hand dictates our approach. If we are interested in the physical disturbance of the air in a room, it is a problem of physics. If we are interested in how that disturbance is perceived by a person listening in the room, psychoacoustical methods must be used. Because this book addresses acoustics in relation to people, both aspects of sound will be considered. That being said, because we are primarily interested in how room materials and geometry affect the disturbance, our investigations will mainly deal with physics.

Sound can be characterized by objective phenomena. For example, frequency is an objective property of sound; it specifies the number of waveform repetitions per unit of time (usually 1 second). Frequency can be readily measured on an oscilloscope or a frequency counter. From a physics standpoint, the concept of frequency is straightforward. We will have much more to say about the objective qualities of sound, particularly in the way that the properties of sound are dictated by the rooms we inhabit.

On the other hand, that rate of repetition can be characterized subjectively. Frequency is then considered in terms of pitch, which is a subjective property of sound. Perceptually, we hear different pitches for soft and loud 100-Hz tones. As intensity increases, the pitch of a low-frequency tone goes down, while the pitch of a high-frequency tone goes up. Harvey Fletcher found that playing pure tones of 168 and 318 Hz at a modest level produces a very discordant sound. At a high intensity, however, the ear hears pure tones in the 150- to 300-Hz octave relationship as a pleasant sound. We cannot equate frequency and pitch, but they are analogous. Another objective/subjective duality exists between intensity and loudness. Similarly, the relationship between waveform (or spectrum) and perceived quality (or timbre) is not linear. A complex waveform can be described in terms of a fundamental and a series of harmonics of various amplitudes and phases. But perception of timbre is complicated by the frequency-pitch interactions in the human hearing mechanism as well as other factors.

The interaction between the physical properties of sound, and our perception of them, poses delicate and complex issues. It is this complexity in audio and acoustics that creates such interesting problems. On one hand, the design of a loudspeaker or a concert hall should be a straightforward and objective engineering process. But in practice,

2 Chapter One

that objective expertise must be carefully tempered with purely subjective wisdom. As has often been pointed out, loudspeakers are not designed to play sine waves into calibrated microphones placed in anechoic chambers. Instead, they are designed to play music in our listening rooms. In other words, the study of audio and acoustics involves both art and science. To learn the complexities of audio and acoustics, we begin with the science, keeping in mind that our ears will ultimately determine the success or failure of our projects.

Simple Harmonic Motion and the Sine Wave

The weight (mass) and the spring shown in Fig. 1-1 comprise a vibrating system. Moreover, the weight moves in what is called simple harmonic motion. When the weight is at rest, the system is said to be in equilibrium. If the weight is pulled down to the -5 mark and released, the spring pulls the weight back toward 0. However, the weight will not stop at 0; its inertia will carry it beyond 0 almost to +5. The displacement of the weight defines the amplitude of the motion.

The weight will continue to vibrate, or oscillate. Each up/down repetition is called a cycle, and the motion is said to be periodic. In the arrangement of a mass and a spring, vibration or oscillation is possible because of the elasticity of the spring and the inertia of the weight. Elasticity and inertia are two things all media must possess to be capable of conveying sound. In this practical example, the amplitude of motion will slowly decrease due to frictional losses in the spring and the air around it.

Harmonic motion is a basic type of oscillatory motion, and it yields an equally basic wave shape in sound and electronics. To illustrate this, if a pen is fastened to the weight's pointer, as shown in Fig. 1-2, and a strip of paper is moved past it at a uniform speed, the resulting trace is a sine wave. The sine wave is a pure waveform closely related to simple harmonic motion. In this figure, the sine wave traced by the pen has completed one full period and is more than halfway through a second period. The periodic motion of the weight will continue to trace the sine wave indefinitely. (For a moment, we are ignoring the frictional losses that would decrease amplitude.) This simple oscillatory system will always create sinusoidal motion; without outside forces, no other motion is

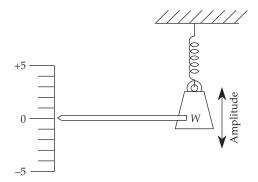


Figure 1-1 A weight on a spring vibrates at its natural frequency because of the elasticity of the spring and the inertia of the weight.

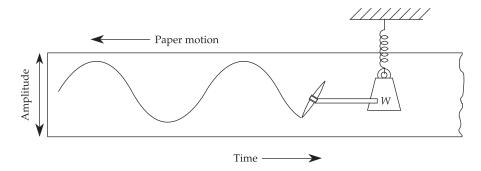


Figure 1-2 A pen fastened to the vibrating weight traces a sine wave on a paper strip moving at a uniform speed. This shows the basic relationship between simple harmonic motion and the sine wave.

possible with this system. However, this graph of a sine wave, showing amplitude versus time, sets precedence for plotting many different wave shapes.

As another example of oscillatory motion, consider a piston in an internal-combustion automobile engine that is connected to the crankshaft by a connecting rod. The rotation of the crankshaft and the up-and-down motion of the pistons illustrate the relationship between rotary motion and linear simple harmonic motion. As with the weight on a spring, the piston position plotted against time produces a sine wave.

Sound in Media

The weight and spring system in the previous example models the motion of air molecules. If an air particle is displaced from its original position, elastic forces of the air tend to restore it to its original position. Because of the inertia of the particle, it overshoots the resting position, bringing into play elastic forces in the opposite direction, and so on.

An elastic medium is essential to the existence of sound waves. Because air is such a common agent for the conduction of sound, it is easy to forget that other media are also conductors of sound. Thus, sound is readily conducted in gases, liquids, and solids such as air, water, steel, concrete, and so on, which are all elastic media. Imagine a railroad track; a friend stationed a distance away strikes a rail with a rock. You will hear two sounds, one sound coming through the rail and one through the air. The sound through the rail arrives first because the speed of sound in steel is faster than in air. Similarly, liquids can be very efficient conductors of sound; underwater sounds can be detected after traveling thousands of miles through the ocean.

Without a medium, sound cannot be propagated. In the laboratory, an electric buzzer is suspended in a heavy glass bell jar. As the button is pushed, the sound of the buzzer is readily heard through the glass. As the air is pumped out of the bell jar, the sound becomes fainter and fainter until it is no longer audible. The sound-conducting medium, the air inside the jar, has been removed between the source and the ear. Outer space is an almost perfect vacuum; no sound can be conducted except in the tiny island of atmosphere within a spaceship or a spacesuit.

4 Chapter One

Particle Motion

Waves created by the wind travel across a field of grain, yet the individual stalks remain firmly rooted as the wave travels on. In a similar manner, particles of air propagating a sound wave do not move far from their undisplaced positions, as shown in Fig. 1-3. The disturbance travels on, but the propagating particles move only in localized regions (with perhaps a maximum displacement of a few ten-thousandths of an inch). Note also that the velocity of a particle is maximum at its equilibrium position, and zero at the points of maximum displacement (a pendulum has the same property). The maximum velocity is called the velocity amplitude, and the maximum displacement is called the displacement amplitude. The maximum particle velocity is very small, less than 0.5 in/sec for even a loud sound. As we will see, to lower the level of a sound, we must reduce the particle velocity.

There are three distinct forms of particle motion. For sound traveling in a gaseous medium such as air, the particles move in the direction the sound is traveling. This motion is described as longitudinal waves, which expand and contract in the direction of propagation, as shown in Fig. 1-4A. As we will see, this oscillation causes high- and low-pressure regions. The instantaneous pressure on opposite sides of a pressure minimum has opposite polarity. The pressure on one side is increasing, whereas the pressure on the other side is decreasing. A second type of wave motion is illustrated by a violin string, as shown in Fig. 1-4B. The tiny elements of the string move transversely, or at right angles to the direction of travel of the waves along the string. Thirdly, if a stone is dropped on a calm water surface, concentric waves travel out from the point of impact, and the water particles trace circular orbits (for deep water, at least), as shown in Fig. 1-4C.

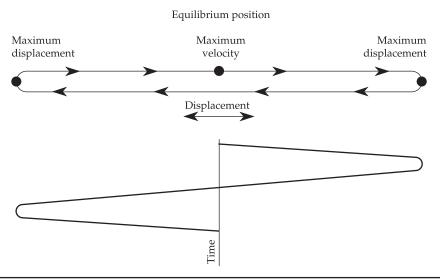


Figure 1-3 An air particle is made to vibrate about its equilibrium position by the energy of a passing sound wave because of the interaction of the elastic forces of the air and the inertia of the air particle.

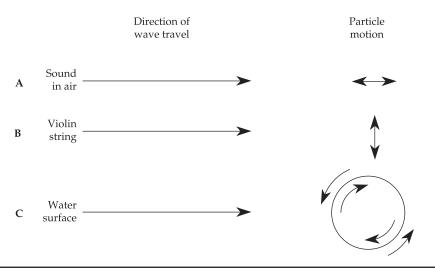


Figure 1-4 Particles involved in the propagation of sound waves can move with (A) longitudinal motion in air, (B) transverse motion on a string, or (C) circular motion on the water surface.

Propagation of Sound

How are air particles, moving slightly back and forth, able to carry music from a loud-speaker to our ears? The dots of Fig. 1-5 represent air molecules with different density variations. The molecules crowded together represent areas of compression (crests in the wave shape) in which the air pressure is slightly greater than the prevailing atmospheric pressure (typically about 14.7 lb/in² at sea level). The sparse areas represent rarefactions (troughs in the wave shape) in which the pressure is slightly less than atmospheric pressure. The arrows (see Fig. 1-5) indicate that, on average, the molecules are moving to the right of the compression crests and to the left in the rarefaction troughs between the crests. Any given molecule, because of elasticity, after an initial displacement, will return toward its original position. It will move a certain distance to the right and then approximately the same distance to the left of its undisplaced position as the sound wave progresses uniformly to the right. Sound propagates because of the transfer of momentum from one particle to another.

In this example, why does the sound wave move to the right? The answer is revealed by a closer look at the arrows (see Fig. 1-5). The molecules tend to bunch up where two arrows are pointing toward each other, and this occurs a bit to the right of each compression region. When the arrows point away from each other, the density of molecules decreases. Thus, the movement of the higher-pressure crest and the lower-pressure trough accounts for the progression of the sound wave to the right.

As mentioned previously, the pressure at the crests is higher than the prevailing atmospheric barometric pressure and lower than the atmospheric pressure at the troughs, as shown in the sine wave of Fig. 1-6. These fluctuations of pressure are very small indeed. The faintest sound the ear can hear (20 μPa) exists at a pressure some 5,000 million times smaller than atmospheric pressure. To summarize, typical sounds such as speech and music are represented by correspondingly small ripples in pressure superimposed on the atmospheric pressure.

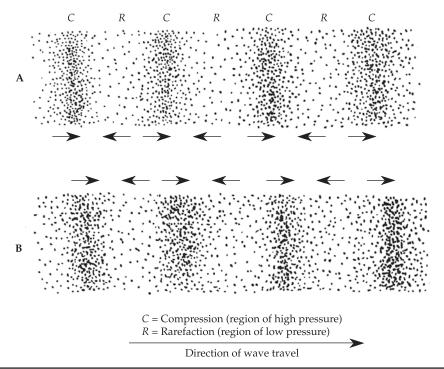


Figure 1-5 Sound waves traveling through a medium change the localized air particle density.

(A) A sound wave causes the air particles to be pressed together (compression) in some regions and spread out (rarefaction) in others. (B) An instant later the sound wave has moved slightly to the right.

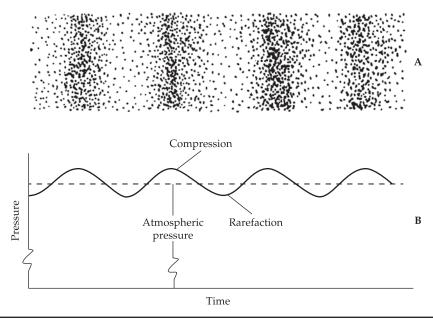


Figure 1-6 Pressure variations of sound waves are superimposed on prevailing barometric pressure. (A) An instantaneous view of the compressed and rarefied regions of a sound wave in air. (B) The compressed regions are very slightly above and the rarefied regions very slightly below atmospheric pressure.

Medium	Speed of Sound (ft/sec)	Speed of Sound (m/sec)
Air	1,130	344
Distilled water	4,915	1,498
Seawater	5,023	1,531
Wood, fir	12,470	3,800
Steel bar	16,570	5,050
Gypsum board	22,310	6,800

 Table 1-1
 Examples of Speed of Sound in Different Materials

Speed of Sound

The speed of sound in air is about 1,130 ft/sec (344 m/sec) at 70°F (21°C). This is about 770 mi/hr (1,239 km/hr). In the field of aerodynamics, this speed is known as Mach 1.0 (technically, it is air speed relative to the local speed of sound). This speed is not particularly fast in relation to familiar things. For example, commercial aircraft routinely travel at speeds that approach the speed of sound; for example, a Boeing 787 jetliner has a cruising speed of 561 mi/hr (Mach 0.85). The speed of sound is dramatically slower than the speed of light (670,616,629 mi/hr). It takes about 5 seconds for sound to travel 1 mile. You can gauge the distance of a thunderstorm by counting the time between the sight of the lightning flash and the sound of its thunder; if you count to 5 seconds, the storm is about a mile away. The speed of sound in the audible range is appreciably affected by temperature and slightly affected by humidity. It is not appreciably affected by the intensity of sound, its frequency, or by changes in atmospheric pressure. In some cases, some factors that would otherwise affect the speed of sound are offset by other factors, yielding insignificant changes.

Sound will propagate at a certain speed that depends on the medium and other factors. Other properties being equal, the stiffer or more rigid a medium, or the less compressible it is, the faster the speed of sound in it. Generally, sound travels faster in liquids than in air, and it travels faster in solids than in liquids. For example, sound travels at about 5,023 ft/sec in seawater and about 16,570 ft/sec in steel. Other examples are shown in Table 1-1. As noted, sound also travels faster in air as temperature increases (an increase of about 1.1 ft/sec for every degree Fahrenheit). Finally, humidity slightly affects the speed of sound in air; the more humid the air, the faster the speed. It should be noted that the speed (velocity) of sound is different from the particle velocity. The speed (velocity) of sound determines how fast sound energy moves through a medium. Particle velocity is determined by the loudness of the sound.

Wavelength and Frequency

A sine wave is illustrated in Fig. 1-7. The wavelength λ is the distance a wave travels in the time it takes to complete one cycle. A wavelength can be measured between successive peaks or between any two corresponding points on the cycle. This also holds for periodic waves other than the sine wave. The frequency f specifies the number of

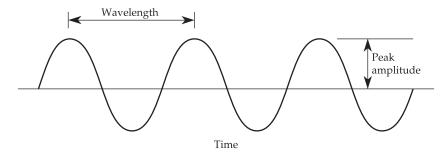


Figure 1-7 Wavelength is the distance a wave travels in the time it takes to complete one cycle. It can also be expressed as the distance from one point on a periodic wave to the corresponding point on the next cycle of the wave.

cycles per second, measured in hertz (Hz). Frequency and wavelength are related as follows:

Wavelength (ft) =
$$\frac{\text{Speed of sound (ft/sec)}}{\text{Frequency (Hz)}}$$
 (1-1)

which can also be written as

Frequency (Hz) =
$$\frac{\text{Speed of sound (ft/sec)}}{\text{Wavelength (ft)}}$$
 (1-2)

As noted, the speed of sound in air is about 1,130 ft/sec at normal conditions. For sound traveling in air, Eq. (1-2) becomes

Wavelength (ft) =
$$\frac{1,130}{\text{Frequency (Hz)}}$$
 (1-3)

This relationship is perhaps the most fundamentally important relationship in audio. Figure 1-8 gives two approaches for a graphical solution to Eq. (1-3).

Complex Waveforms

Speech and music wave shapes depart radically from the simple sine wave and are considered as complex waveforms. However, no matter how complex the waveform is, as long as it is periodic, it can be reduced to sine components. The obverse of this states that any complex periodic waveform can be synthesized from sine waves of different frequencies, different amplitudes, and different time relationships (phase). Joseph Fourier was the first to prove these relationships. The idea is simple in concept but often complicated in its application to specific speech or musical sounds. Let us see how a complex periodic waveform can be reduced to simple sinusoidal components.

Harmonics

A simple sine wave of a given amplitude and frequency, f_1 , is shown in Fig. 1-9A. Figure 1-9B shows the second harmonic sine wave f_2 that is twice the frequency and half the amplitude of f_1 . Combining f_1 and f_2 at each point in time, the wave shape of

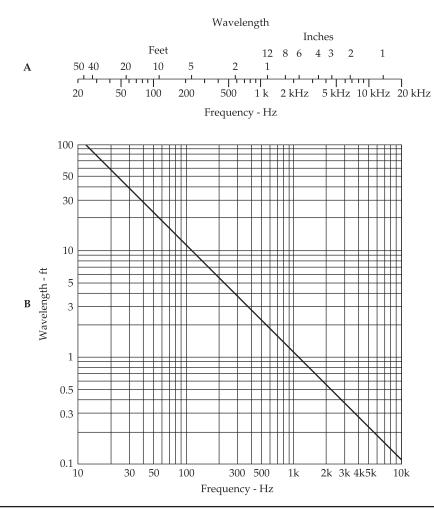


Figure 1-8 Wavelength and frequency are inversely related. (A) Scales for approximately determining wavelength of sound in air from a known frequency or vice versa. (B) A chart for determining the wavelength in air of sound waves of different frequencies. (Both are based on the speed of sound of 1,130 ft/sec.)

Fig. 1-9C is obtained. Figure 1-9D shows the third harmonic sine wave f_3 that is three times the frequency and half the amplitude of f_1 . Adding this to the f_1+f_2 wave shape of C, Fig. 1-9E is obtained. The simple sine wave of Fig. 1-9A has been progressively changed as other sine waves have been added to it; this is valid for both acoustic waves and electronic signals. The process can be reversed. The complex waveform of Fig. 1-9E can be disassembled, as it were, to the simple f_1 , f_2 , and f_3 sine components by either acoustic or electronic filters. For example, passing the waveform of Fig. 1-9E through a filter permitting only f_1 and rejecting f_2 and f_3 , the original f_1 sine wave of Fig. 1-9A emerges in pristine condition.